Algebraic Topology

Algebrait Topology builds "functions" (actually functors) (Topological spaces,) ⇒ (algebraic things,) vector spaces (continuous maps) (algebraic maps) the main point is to show two topological spaces are different C.g. Rⁿ ∉ R^m it n ≠m ~ homeomorphic \mathbb{R}^3 - $\bigcirc \not\cong \mathbb{R}^3$ - \bigcirc but can use alg. top. for many other things 1) maps between spaces · does a given space M embed in N? eg for what m does RP" embed in R"? (answer not known wigeneral!) · can you "lift" a map? re given $f: A \rightarrow B$ and $\pi: E \rightarrow B$ does there exist f: A→E st. Tof=f? this includes 3 of sections of bundles

but before we start we will develop so important ideas that will be used throughout the course

O. Homotopy and CW Complexes

A. <u>CW complexes</u>

We develop alg. top. for all topological spaces, but a convenient (and very large) class of spaces to study ore (W complexes

let D' C IR' be the unit disk

5ⁿ⁻¹ = ∂Dⁿ its boundary given • Y a topological space and maps will be assumed to be • a: sⁿ⁻¹→Y a continuous map Continuous even it it is not stated the space obtained from Y by attaching an n-cell (via a) is

 $Y U_a D^n = Y \perp D^n_{\{x \sim a(x)\}}_{x \in S^{n-1}}$ $D^n_{a(S^{n-1})} Y U_a D^n \text{ is given the quotient}_{topology}$

An <u>n-complex</u>, or <u>n-dimentional</u> <u>CW complex</u> is defined inductively by a (-1) complex is Ø an n-complex Xⁿ is any space obtained from an (n-1)-complex Xⁿ⁻¹by attaching n-cells if $X = \bigcup_{n=0}^{\infty} x^n$, where X^n is an n-complex obtained by attaching n-cells to X^{n-1} the we say X is an infinite dimensional complex we say a CW complex is finite if it only involves a finite number of cells the <u>k-skeleton</u> of X, is the union $X^{(k)}$ of all 1-cells for $1 \leq k$ <u>Remarks:</u> i) C. vi CW shade for closure finite and with means the

1) C in CW stands for <u>closure</u> finite and just means the closure of each cell is contained in the union of finitely many cells

2) W in CW stands for weak topology and means a set S

in X is open ⇒ Sn X^(h) open for all k
(this is automatic if X is finite dimensional)

3) CW complexes are Hausdorff spaces (see Hatcher)
<u>Exercise</u>: Show the product of CW complexes is a CW complex.

Examples:

- 1) I-dim CW complexes are graphs
- 2) Surfaces are CW complexes



a <u>subcomplex</u> of a CW complex X is a closed subspace ACX that is a union of cells in X note A is a CW complex too (X,A) is called a <u>CW pair</u>

B Homotopy

A fundamental notion in algebraic topology is homotopy and homotopy equivalence

let X and Y be topological spaces two maps $f, g: X \rightarrow Y$ are <u>homotopic</u>, $f^{\prime}g, if$ there is a continuous map $\overline{\Phi}: X \times [o, \mathcal{I} \longrightarrow \mathcal{V}]$ 1 is called a homotopy) S.t. $f(x) = \overline{\phi}(x,o) \quad \forall x \in X$ g(x)=∮(x,1) ∀x ∈X <u>Remarks</u>: 1) \oint gives a family of maps $\phi_t: X \rightarrow Y$ where $\phi_t(x) = \oint(x, t)$ these maps are "continuous in t" in the sence that Φ is continuous. so maps are homotopic if we can continuously deform one into the other 2) if ACX, then we say the homotopy from f to g is relative to A, denoted f ~ g, it in oddition to above $\overline{\Phi}(x,t) = f(x) = g(x) \quad \forall x \in A, t \in [0,1]$ 3) if A < X and B < Y, then the notation f: (X, A) -> (Y, B) means $f: X \rightarrow Y$ is a map and $f(A) \subset B$ we say f is a map of pairs If $f, g: (X, A) \rightarrow (Y, B)$, then they are homotopic (as maps of pairs) if] a homotopy st. each of is a map of pairs <u>Example</u>: for any space X any map f: X -> Eo.1] is homotopic to the constant map g(x)=0 the homotopy is $\Phi: X \times [0,1] \longrightarrow [0,1]$ $(x,t) \longmapsto (i-t) f(x)$

Exercise: homotopy is an equivalence relation on maps
$$X \rightarrow Y$$

let $C(X,Y) = \{ \text{continuous maps } X \rightarrow Y \}$
 $[X,Y] = C(X,Y) / [- homotopy] = \{ \text{homotopy classes of maps } X \rightarrow Y \}$
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 $[X,Y] = C(X,Y) / [- homotopy] = \{ \text{gold = o} \}$
i) for any X
 $[X, [0,1]] = \{ \text{gold = o} \}$
2) for any X
 $[[Y,X]] = \{ \text{path components of } X \}$
 one point space
We call a space X pointed if it has a "base point" $x_0 \in X$
 $\{ \text{just some prechosen fixed point"} \}$
 $[X,Y]_0 = \{ \text{homotopy classes of maps of pairs } (X, \{x_i\}) \rightarrow (X, \{x_i\}) \}$
let y_0 be the north pole w_1 the n-sphere S^n
 $(n.e. S^n = onit sphere w_1 \mathbb{R}^{n+1}
 $y_0 = (o_1, \dots, o_1) \}$
the nth homotopy group of a (pointed) space (X, x_0) is
 $T_n(X, x_0) = [S^n, X]_0$
these are all groups and we will spend some time studying $T_1(X, x_0)$ which is also called the fundamental group$

Question: For what Y is [Y,X], "naturally" a group for all X? For what Y is [X,Y], "naturally" a group for all X?

Note: given a map
$$f: X_i \rightarrow X_z$$
 there is a natural function
 $f_*: [Y_i, X_i] \rightarrow [Y_i, X_i]: g \mapsto f \circ g$
and
 $f^*: [X_{i_1}, Y] \rightarrow [X_{i_1}, Y]: g \mapsto g \circ f$
(Proof: just compose homotopy with f)
Rimk: Natural in question above means f_* , resp f^* , is a homomorphism
We say $f: X \rightarrow Y$ is the homotopy inverse of
 $g: Y \rightarrow X$ if $f \circ g \sim id_Y$ and $g \circ f \sim id_X$
if $g: Y \rightarrow X$ has a homotopy inverse then we say g is a homotopy
equivalence and we say X and Y are homotopy equivalent
or have the same homotopy type and write $X \simeq Y$
Exercise: This is an equivalence relation

3) for any space
$$Z$$
 there is a one-to-one correspondence
 $\phi^{Z}: [Z, X] \rightarrow [Z, Y]$
such that for all continuous $h: Z \rightarrow Z'$
 $[Z, X] \xrightarrow{\phi^{Z'}} [Z, Y]$
 $\downarrow h^{*} \qquad \downarrow h^{*}$
 $[Z, X] \xrightarrow{\phi^{Z}} [Z, Y]$

<u>Remark</u>: So two spaces are homotopy equivalent iff homotopy classes of maps to and from the spaces are "naturally equivalent" <u>Examples</u>:

0) if X and Y are homeomorphic, then they are homotopy equivalent.

1)
$$X = 5'$$
 is homotopy equivalent to $Y = 5' \times [0,1]$
indeed: $f: X \to Y: x \mapsto (x, 0)$
 $g: Y \to x: (x, s) \mapsto x$
note: $g \circ f = i d_X$
 $f \circ g \sim i d_Y$ by $\phi_t: Y \to Y: (x, s) \mapsto (x, ts)$

2) A space X is called <u>contractible</u> it it has the homotopy type of a point.

e.g. $\mathbb{R}^n \simeq \{ * \}$ (exercise)

3) if ACX then a <u>retraction</u> is a map r: X→A such that r(x)=x tx ∈ A a <u>deformation</u> <u>retraction</u> of X to A is a homotopy, relA, from the identity on X to a retraction:

$$\phi_t : X \to X \quad t \in [0, 1]$$

$$\phi_0(x) = x \quad \forall x \in X$$

$$\phi_1(X) \subset A$$

$$\phi_1(x) = x \quad \forall x \in A \text{ and } t$$

note: If X deformation retracts to A then $X \cong A$ indeed let $\cdot \phi_t$ be homotopy above $\cdot i: A \longrightarrow X$ the inclusion map then i and ϕ_i are homotopy inverses

Since
$$\phi_i \circ i = i \partial_A$$
 and $1 \circ \phi_i = \phi_i \sim \phi_i = i \partial_X$

given spaces X, Y and
a map
$$f: X \rightarrow Y$$

the mapping cylinder M_{f} is
 $M_{f} = (X \times [o, i]) \amalg Y$
where $(X, i) \sim f(X)$
note: M_{f} deformation retracts to Y
indeed $\widetilde{\phi}_{f}: \stackrel{(X, S) \in X \times [o, i]}{Y \in Y} \mapsto (X, (i-t)s+t) \in X \times [o, i]}$
induces maps $\phi_{f}: M_{f} \rightarrow M_{f}$ s.t. $\phi_{o} = id_{M_{f}}$
 $\phi_{i}(M_{f}) \in Y$
 $\phi_{f}(Y) = Y \quad \forall Y \in Y$



examples

1) X a graph A = any edge connecting distinct verticies $\begin{cases} X_A \simeq X \\ A \end{array}$ so any connected graph is homotopy equivalent to a wedge of circles χ 5'v 5'v...v 5' ×_{/A} = vedge of 5'5 `A maximal tree (X, x0) V (Y, Y0) 2) = × 11 4/ (x-16) X = = S²/poles identified X/_A ≅ ×⁄_B ≅ ≅ 5² v 5' $X_{A} \simeq X \simeq X_{B}$ 3) X と TIV AN A٩ $\left(\left(X_{A} \right)_{A_{1}} \right)_{A_{2}}$ Y/B C B Y/_C

To prove both lemmas we need the homotopy extention property
(HEP)
A space X and a subspace
$$A \in X$$
 has the HEP if
whenever we have a map $F_0: X \rightarrow Y$
and a homotopy $f_{\xi}: A \rightarrow Y$ of $f_0 = f_0|_A$
then we can extend the f_t to $F_t: X \rightarrow Y$
lemma 4:
A pair (X, A) has the HEP \Leftrightarrow (X * foillu(A * io, i)) is a retract of X * io, i]
see Hatcher for general case
Proof: (\Leftarrow) we assume A is closed (not nec. but makes proof easier and
given the retract $r: X \times io, i \rightarrow X$ and homotopy $f_t: A \rightarrow Y$ of $f_0 = f_0|_A$
note this defines a map $F_0: (X \times io)! u(A \times io, i) \rightarrow Y$

F is continuous since A is closed
now For:
$$X \times [0,1] \rightarrow Y$$
 is the desired homotopy!
(\Rightarrow) Consider the identity map $F: X \times [0] \cup A \times [0,1] \rightarrow X \times [0] \cup A \times [0,1]$
this gives $F_0: X \rightarrow X \times [0] \cup A \times [0,1]$ by $F|_X$
and $f_t: A \rightarrow X \times [0] \cup A \times [0,1]$ by $f_t = F|_{A \times [t]}$
so $HEP \Rightarrow \exists F_t: X \rightarrow X \times [0] \cup A \times [0,1]$
the F_t give a map $r: X \times [0,1] \rightarrow X \times [0] \cup A \times [0,1]$
(x,t) $t \rightarrow F_t(x)$
that is clearly a retraction

Proof:
Main point: for any disk
$$D^n$$
 there is a deformation
retraction of $D^n \times [o_i]$ to $D^n \times [o_i] \cup \partial D^n \times [o_i]$
Pf: let $D^n \subset \mathbb{R}^n = \mathbb{R}^n \times [o_i] \subset \mathbb{R}^{n+1}$
so $D^n \times [o_i] \subset \mathbb{R}^{n+1}$
let $p = (0, 0, ..., 0, 2)$
given $x \in D^n \times [o_i]$ let $l_x = line through x and p$
and set $\tilde{r}(x) = l_x \cap (D^n \times [o_i])$
unique point!
clear \tilde{r} is a retraction (need to chech containous
and $\tilde{r}_t = t\tilde{r} + [l-t] \log D^n \times [o_i]$
is a deformation retraction.

We define
$$r$$
 on $X^{(0)} \times [0, 1] \longrightarrow [X \times [0]] \cup (A \times [0, 1])$ as follows
if a vertex $D^{\circ} \subset A$, then let r be the identity on $D^{\circ} \times [0, 1]$
if $D^{\circ} \& A$, then let r send any point in $D^{\circ} \times [0, 1]$ to
 $D^{\circ} in X \times [0]$
now inductively assume we have defined r on the $(k-1)$ sheleton
of X , that is $X^{(k-1)} \times [0, 1] \longrightarrow X \times [0] \cup A \times [0, 1]$
for each k cell D^{h} of X
if $D^{h} \subset A$ then let r be the identity map on $D^{h} \times [0, 1]$
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if $D^{h} \subset A$ then let r be the identity map on $D^{h} \times [0, 1]$
where r is already defined
and we have an "inclusion"
 $D^{n \xrightarrow{i}} \times X^{(n-1)} \cup D^{n \xrightarrow{i}} X^{(n-1)} \cup D^{n} \xrightarrow{i} X^{(n-1)}$
where $a: \partial D^{n} \rightarrow X^{(n-1)}$ is the attaching
map for D^{n}
so we have a map $D^{n} \times [0, 1] \longrightarrow X^{(n)}$
 $for composing \tilde{r} above with the above maps extends
 r over $D^{m} \times [0, 1]$
and eventually all of $X^{(n)} \times [0, 1]$
 $Proof of lemma 2:$ Actually we show for any pair $[X_1A)$ satisfying
 HEP with A contractible, the quotient map
 $q: X \rightarrow X/A$ is a homotopy equivalence
for this note there is a homotopy $f_{1}: A \rightarrow A \subset X$ st $f_{0}: dA$
 $note $f_{0}: f_{0}' / A$ is a homotopy equivalence$$

So HEP gives a homotopy
$$F_t: X \to X$$
 extending f_t
Since $F_t(A) \subset A$ for all t we get maps $\overline{F}_t: X|_A \to X|_A$
 $X \xrightarrow{F_t} X$
 $q \downarrow \circ \downarrow q$
 $X|_A \xrightarrow{F_t} X|_A$

also $F_{i}(A) = pt$ so F_{i} also gives a map $h: \frac{X}{A} \to X$ $X \xrightarrow{F_{i}} X$ $g \downarrow \circ h \circ f_{i} \neq f_{i}$ $\frac{Y}{A} \xrightarrow{F_{i}} \frac{Y}{F_{i}} \times \frac{Y}{A}$ you can easily check $h \circ g = F_{i}$ and $g \circ h = \overline{F_{i}}$ but now $h \circ g = F_{i} \sim F_{0} = id_{X}$ $g \circ h = \overline{F_{i}} \sim \overline{F_{0}} = id_{X}$ $\overline{F_{0}} = id_{X}$

Proof of lemma 3:
Recall we have
$$(X,A)$$
 and maps $f,g:A \rightarrow Y$
that are homotopic
let $F:A \times [o,1] \rightarrow Y$ be the homotopy
now let $M_F = X \times [o,1] \cup_F Y$
claim M_F deformation retracts to $X \cup_F Y$ and $X \cup_G Y$
 $\therefore X \cup_F Y \simeq X \cup_G Y$
from lemma 5 we have a
deformation retraction of
 $X \times [o,1]$ to $X \times [o] \cup A \times [o,1]$
exercise: $(X \times [o] \cup A \times [o,1]) \cup_F Y$
 $X \cup_F Y$

given this we see the above deformation retraction induces a deformation retraction of MF to XU,Y

Proof of lemma 5 also shows X×[0,1] deformation retracts onto X×{1} UA×{0,1]

<u>exercise</u>: $(X \times \{i\} \cup A \times \{o, i\}) \cup Y \cong X \cup Y$

so as above M_F = XuyY